

A Design Methodology for Domain-Optimized Power-Efficient Supercomputing

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John Shalf, John Wawrzynek, Samuel Williams

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SC09, Nov 19, 2009

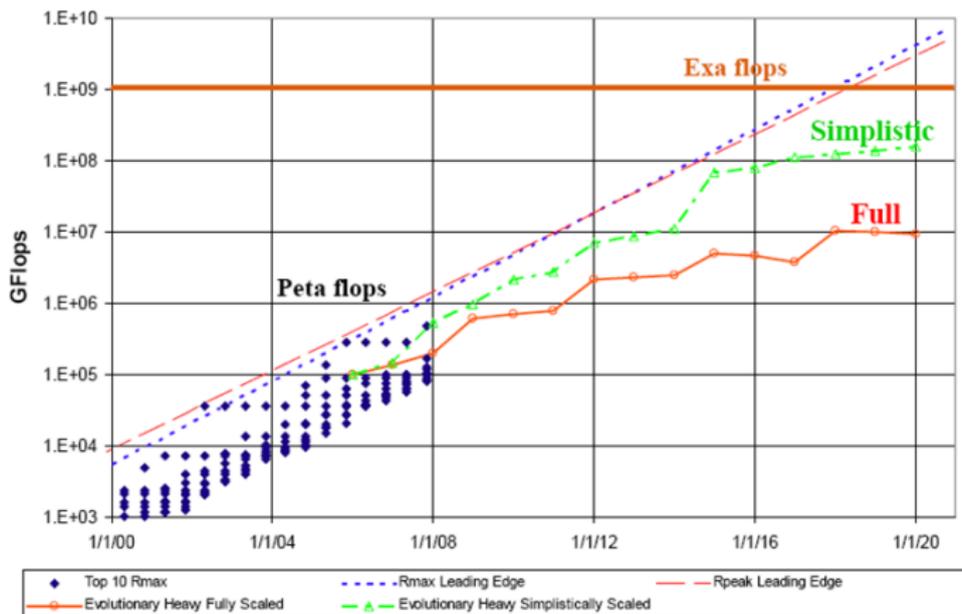
- HW/SW co-tuning as a new approach to HW design
- Applied the new approach to 3 scientific computing kernels and the Stanford Smart Memories multiprocessor
- Results show efficiency improves significantly when HW designed using co-tuning

- 1 Background
- 2 Experimental Setup
- 3 Results
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Will exascale happen?

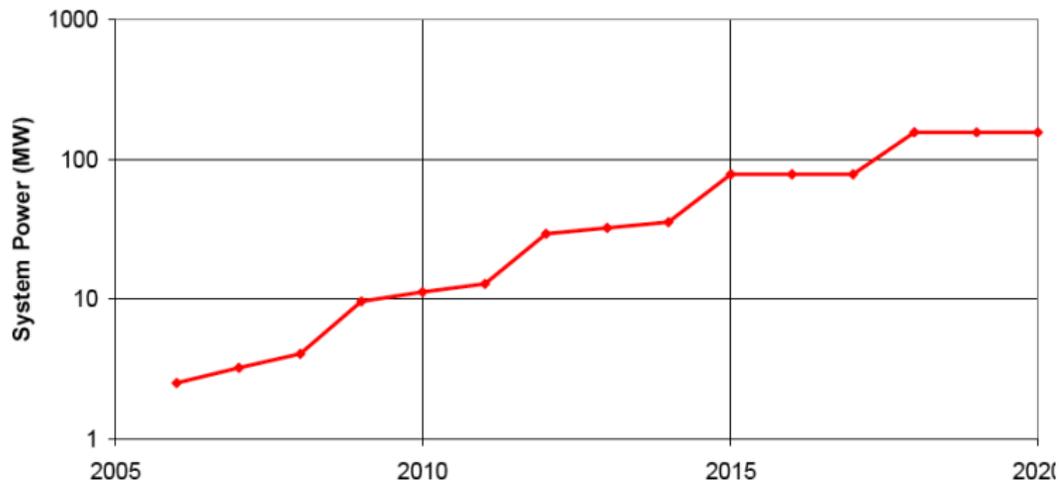
...with the current approach



From Peter Kogge, DARPA exascale study

At what cost?

- Power-efficiency not improving at historic rates
- Petaflop systems already draw Megawatts of power
- DARPA exascale study predicts > 100 Megawatts of power for exaflop systems



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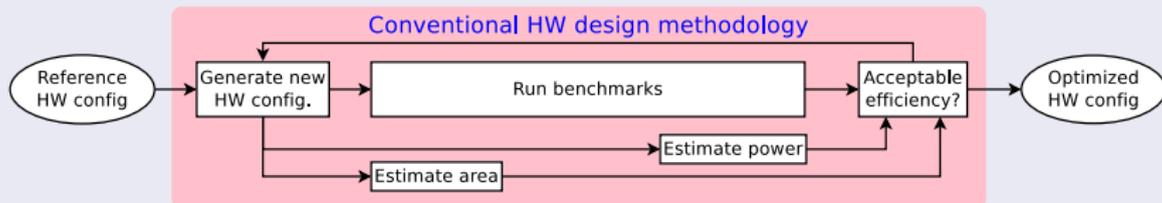
What is wrong with current HW design approaches?

- General-purpose commodity processors in many large machines are power-inefficient
- HW customization improves energy efficiency
 - Simpler cores more power-efficient
 - Intel Core2 sc: 15W@1000 MHz
Tensilica XTensa DP: .09W@600 MHz

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Typical HW design space exploration



- HW config parameters: # cores, cache/local store organization, interconnect, DRAM latency/bandwidth, etc
- Find the right balance of parameters: cores vs. cache, bandwidth vs. peak flop rate
- Benchmarks not optimized for each HW config considered

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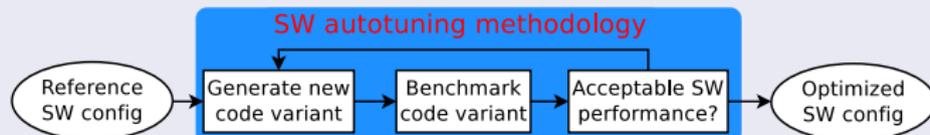
- Automate the process of optimizing SW for a variety of architectures
 - Assumption: architectures evolve \Rightarrow optimizations still valid
- Key to portable high-performance libraries: ATLAS, OSKI, FFTW, SPIRAL

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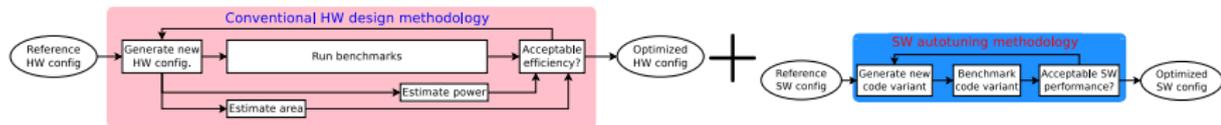
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Conventional SW autotuning

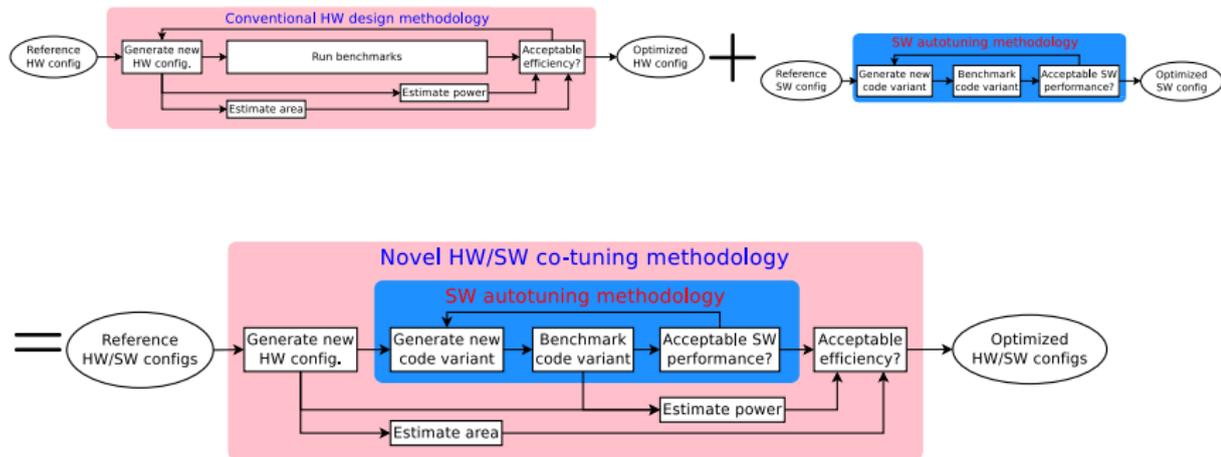


- SW config parameters: register/cache block sizes, loop unroll factor, data structures, algorithms, etc
- Source code generators + parameterized routines + search heuristic
- Offline (install time), runtime tuning

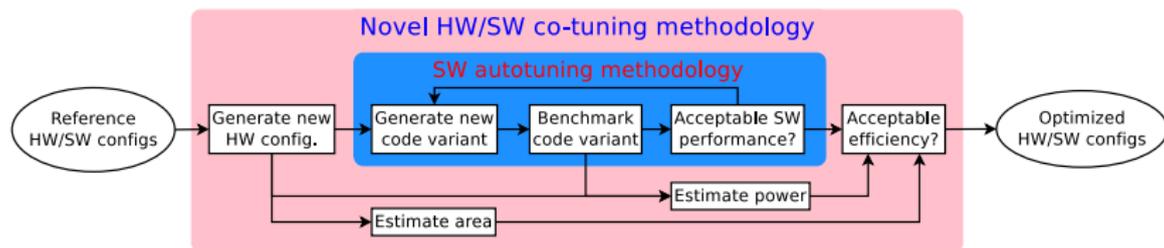
HW/SW Co-tuning: The solution



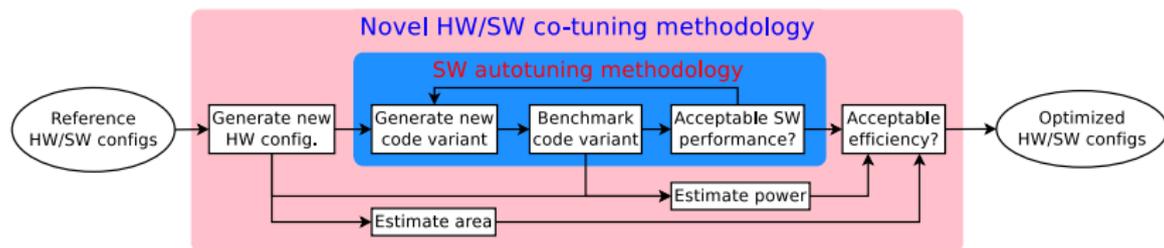
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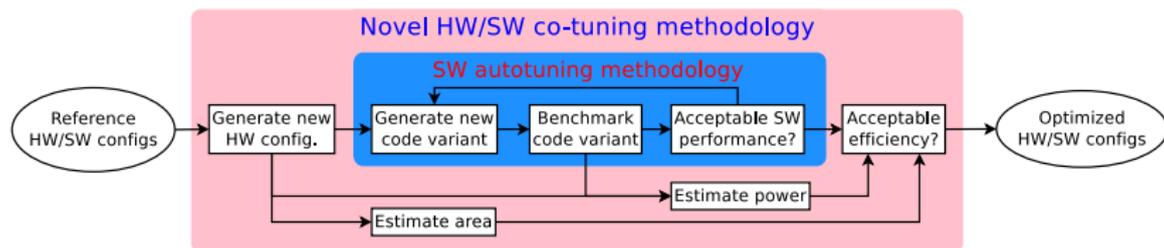
HW/SW Co-tuning



- Key idea: include SW autotuning in the loop for HW design
- A rigorous systematic approach to HW design
- This is also the approach taken in Green Flash where the target application is climate modeling
 - Our results affirm the effectiveness of co-tuning



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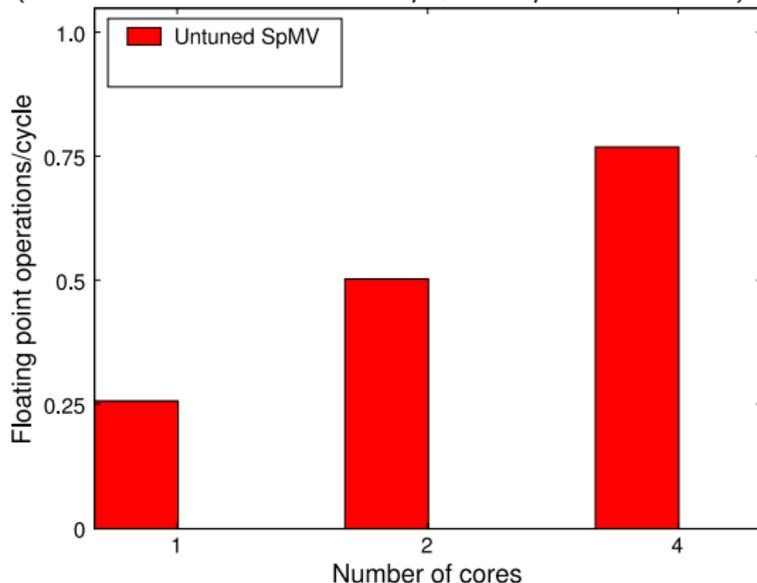


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A simple example

Sparse matrix vector multiply performance (121K rows, nnz/row=27.3) on Stanford Smart Memories multiprocessor

(DRAM bandwidth = 1.6 GB/s, cache/core = 64 KB)

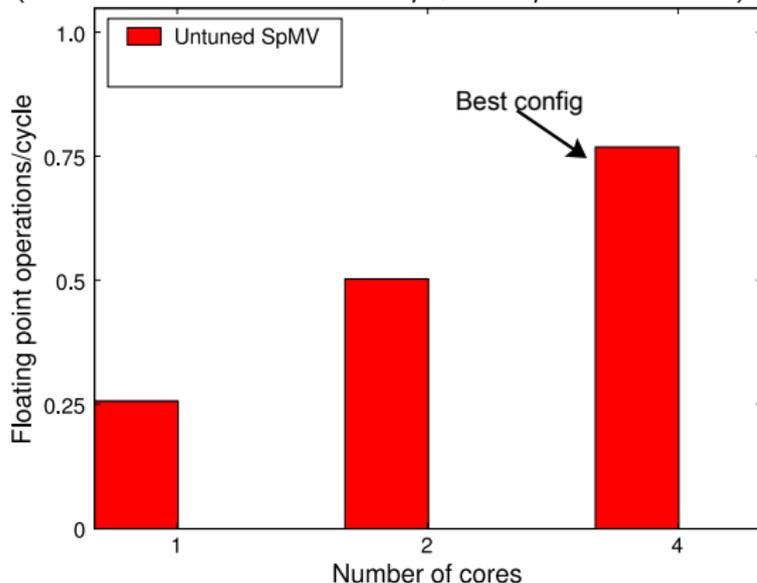


- For tuned SpMV, best #cores = 2 (same performance as 4 cores with half the area)
- For untuned SpMV, best #cores = 4 \Rightarrow overdesign

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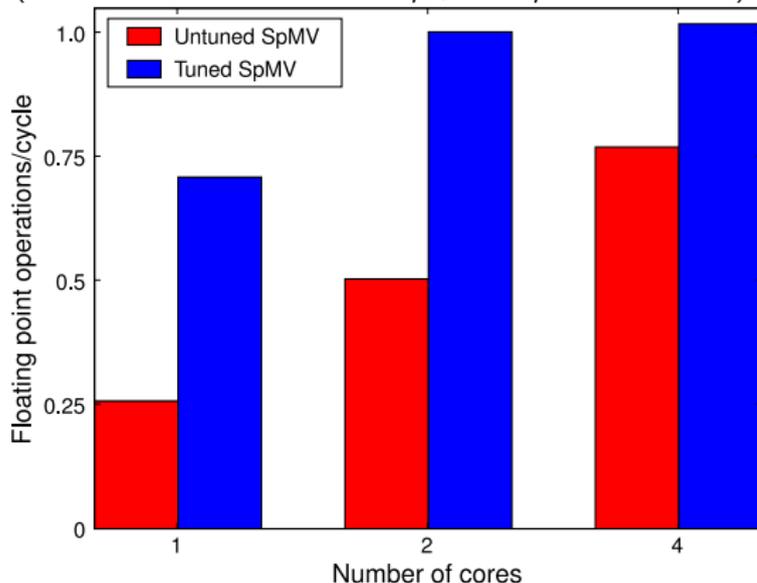


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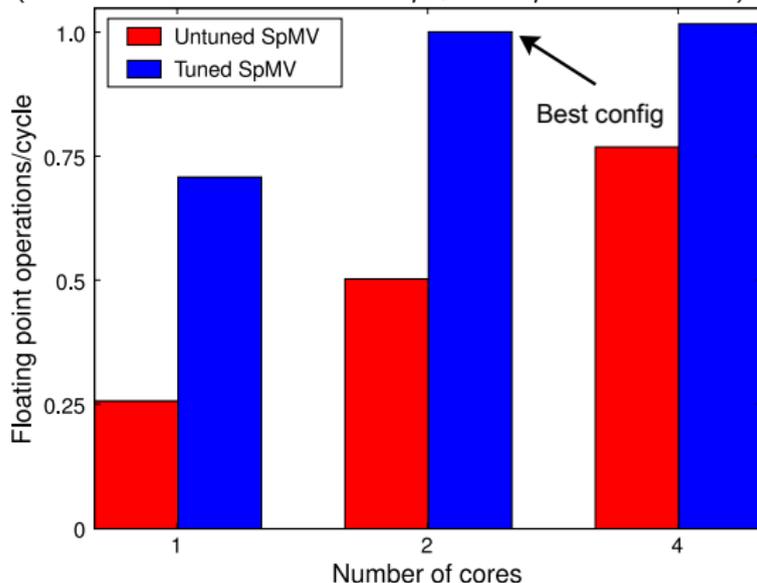


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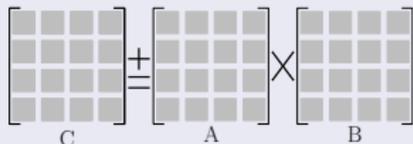
Outline

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- 2 Experimental Setup
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- Software: 3 kernels from scientific computing:
 - Dense matrix matrix multiplication (dense linear algebra)
 - 7pt stencil operator (heat equation PDE)
 - Sparse matrix vector multiplication (sparse linear algebra)
 - Varying computational characteristics
 - ⇒ pull HW parameters in diff. directions
 - Success of co-tuning demonstrated by application on multiple kernels
- Hardware: Stanford Smart Memories multiprocessor
 - Multiprocessor using Tensilica cores
 - Analogous to the Green Flash design which uses the same cores

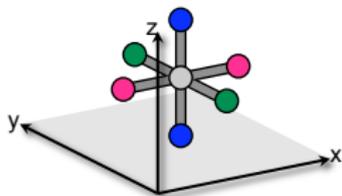
The Kernels

Dense matrix matrix multiplication (GEMM)



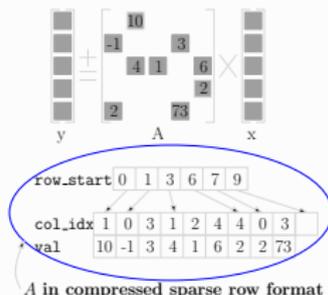
- Dense linear algebra
- High computational intensity
- Tuned code gets close to machine peak
- More cores \Rightarrow better performance
- $2N^3$ flops for multiplying $2 N \times N$ matrices
- $12N^2$ bytes compulsory memory traffic

7-pt stencil operator on 3D grid



- Explicit finite-difference method for the heat equation
- Low computational intensity, regular memory accesses
- More bandwidth \Rightarrow better performance
- $8N^3$ flops on an $N \times N \times N$ grid
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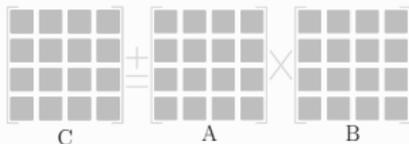
Sparse matrix vector multiplication (SpMV)



- Used in PDEs, sparse solvers
- Low computational intensity, irregular memory accesses
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- $2 \cdot nnz$ flops ($nnz = \#$ nonzeros)
- $4 \cdot nnz$ bytes compulsory memory traffic

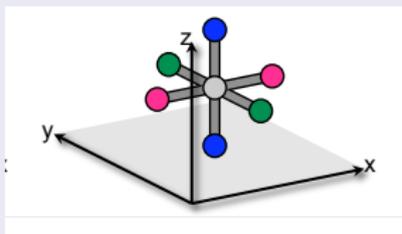
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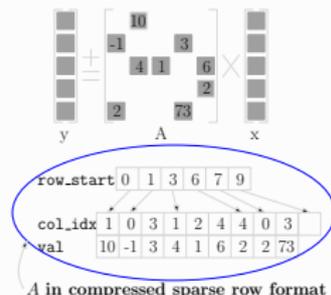
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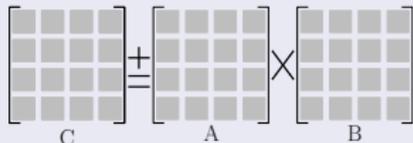
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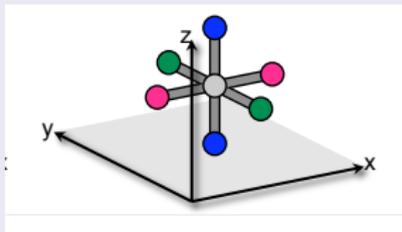
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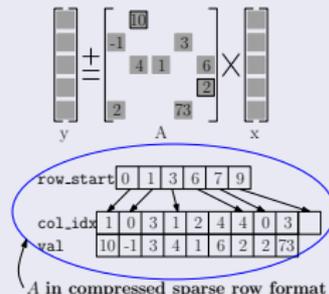
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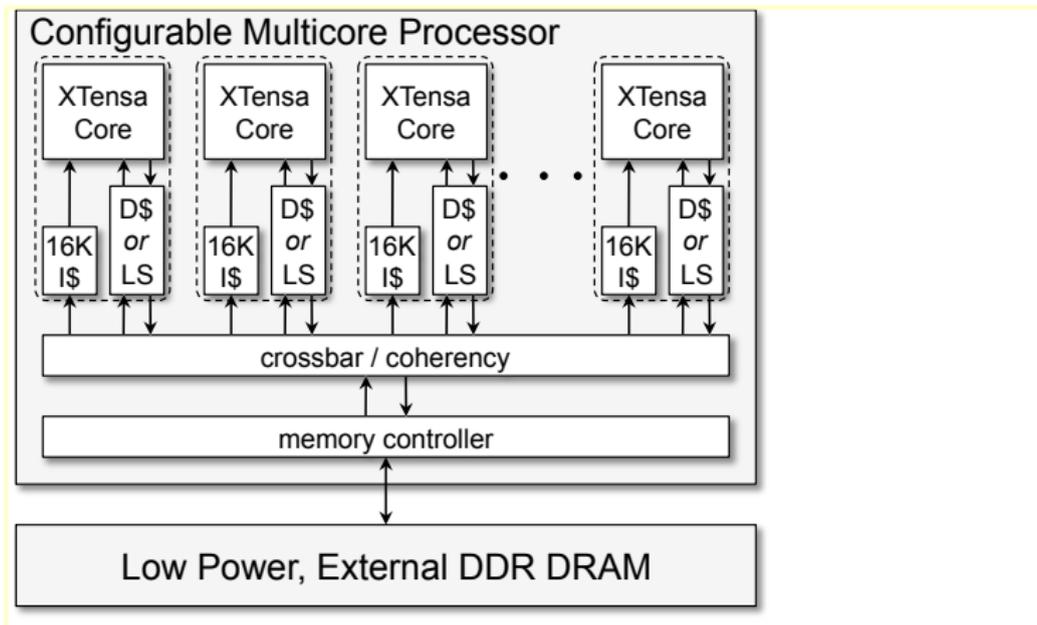
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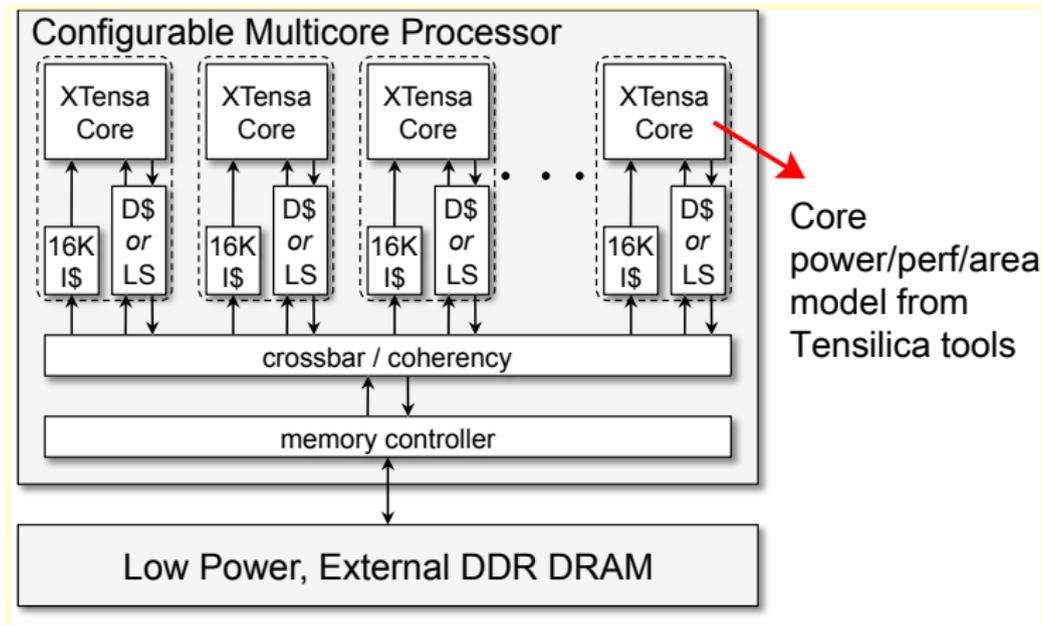
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The Hardware: Stanford Smart Memories Multiprocessor



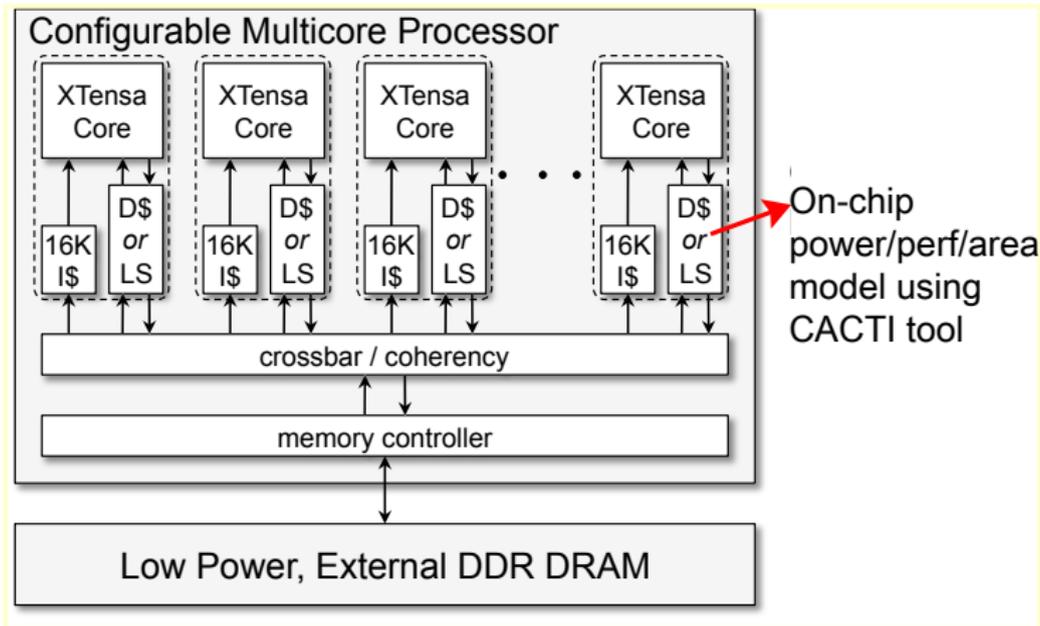
- Each core has a single-precision FPU
- Constant 'area' of 35mm² added to include the impact of DRAM cost

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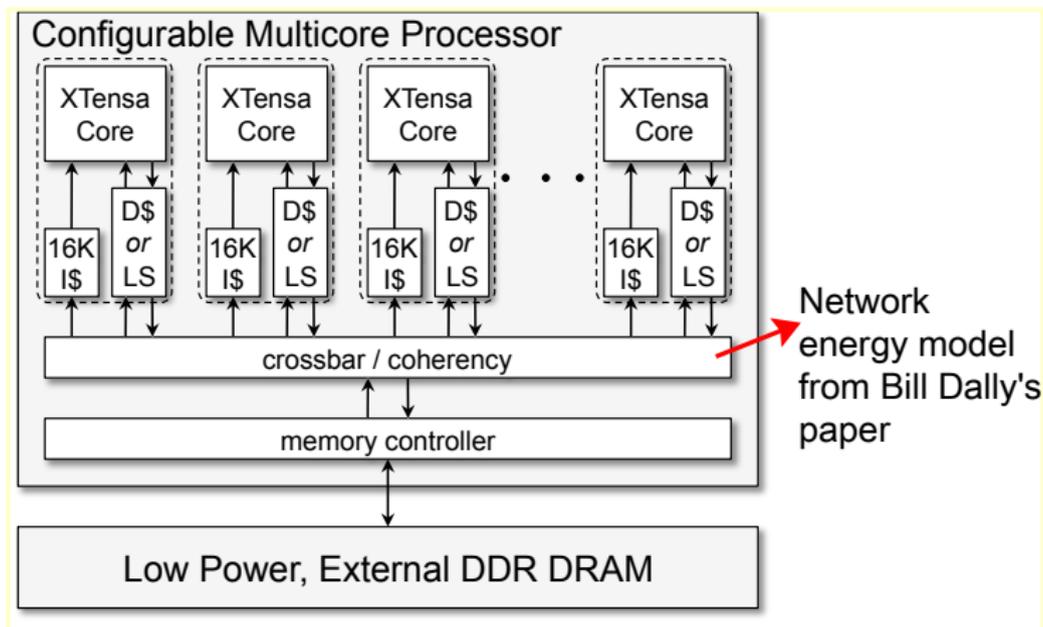
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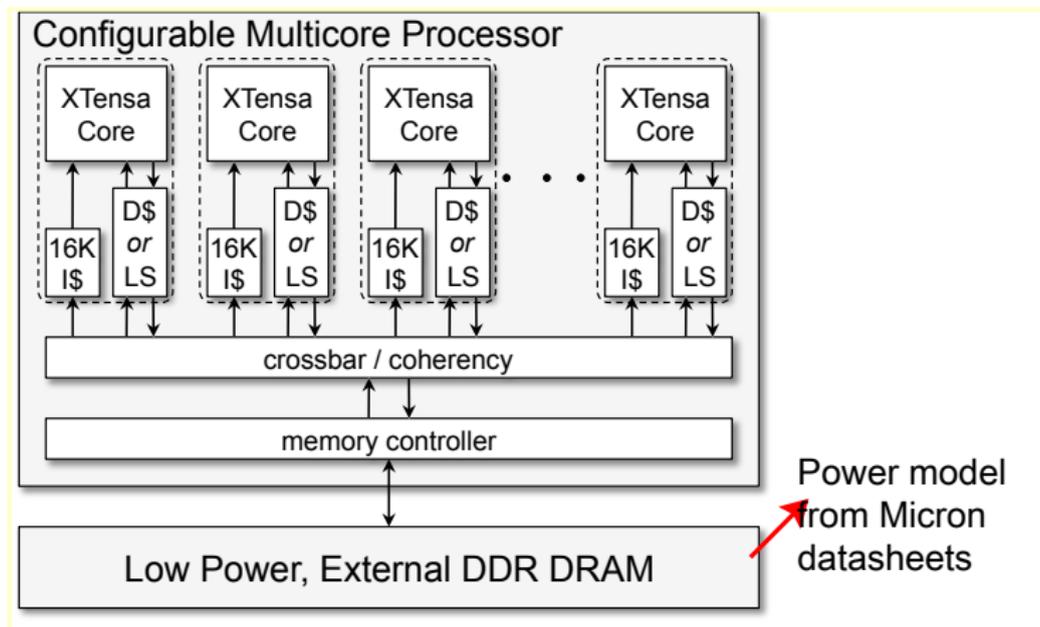
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Hardware Parameters

- **Fixed:**

- Core: single-issue, 500 MHz
- Cache/local store: 16 KB l-cache, cache associativity = 4, linesize = 64 bytes
- DRAM: latency = 100 core cycles

- **Variable:**

- # cores: 1/4/16
- On-chip data memory type: cache/local store
- Cache/local store per core: 16, 32, 64, 128 KB
- DRAM bandwidth: 0.8, 1.6, 3.2 GB/s
- 72 HW configs

- **Baseline config:** Fastest HW

- On-chip memory type: cache
- Cache per core: 128 KB
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Optimized Metrics

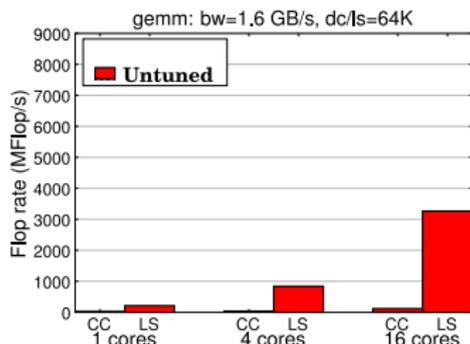
- Focus on scientific computing apps running on large-scale systems
 - Emphasize node efficiency instead of node performance
- Power efficiency (MFlops/Watt)
 - Running costs
 - Maximize performance given a power budget
- Area efficiency (MFlops/mm²)
 - System cost, reliability dependent on area
 - Maximize performance given an area budget
- Power efficiency, area efficiency can result in different optimal HW config
- In general, would want to optimize a combination of power-, area-efficiencies

Effect of SW tuning on performance

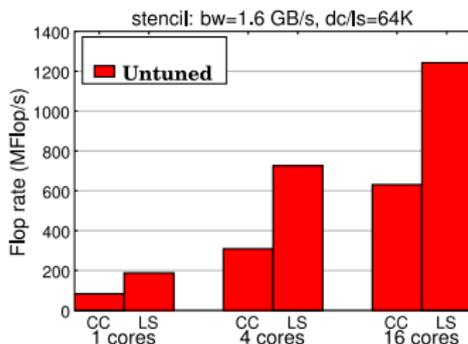
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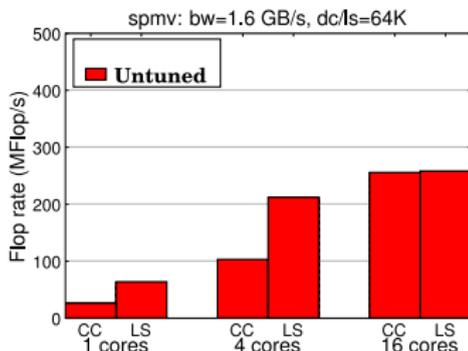
GEMM



Stencil



SpMV

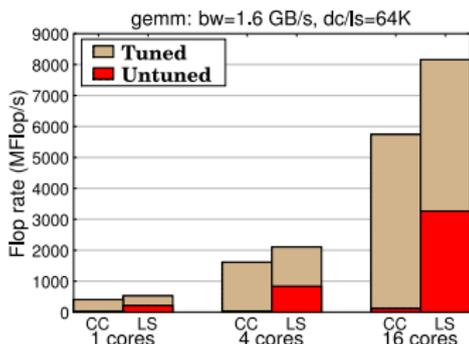


- GEMM gains a lot from tuning
- Software-managed caches get better performance
- Bandwidth-saturation for stencil and SpMV

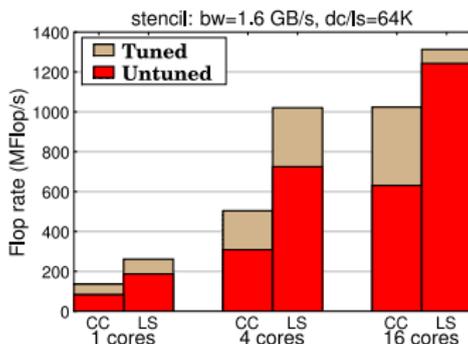
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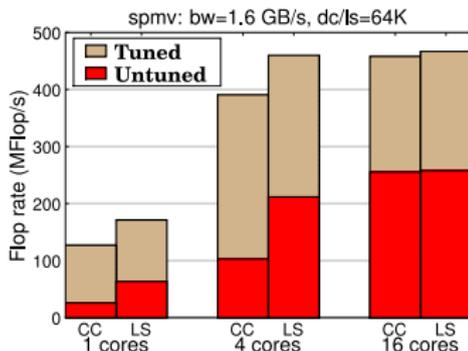
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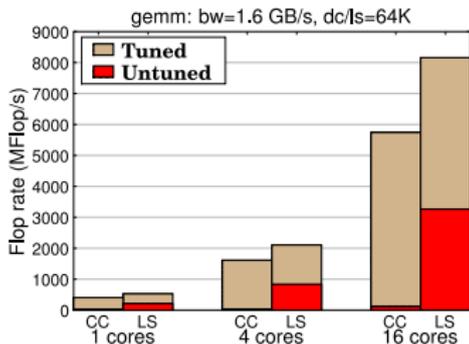
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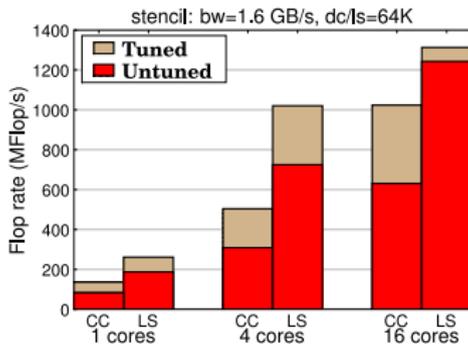
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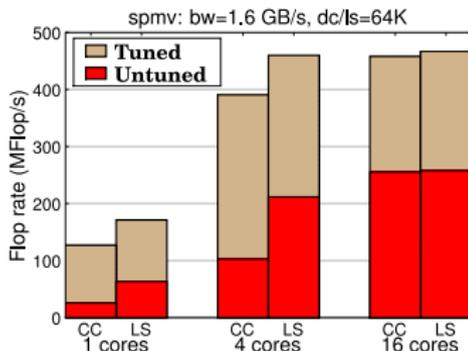
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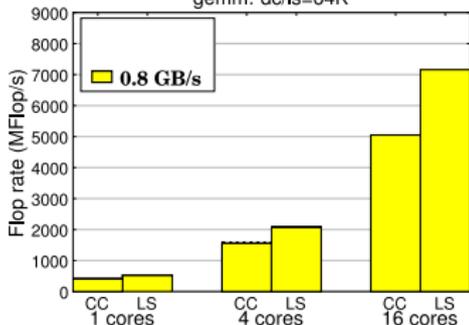
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Effect of memory bandwidth on tuned performance

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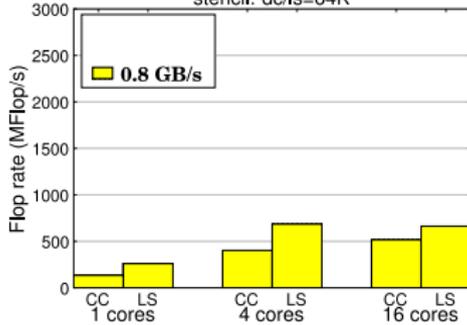
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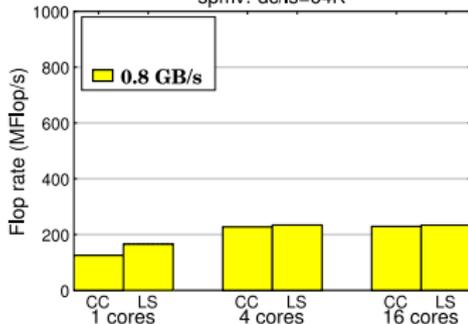
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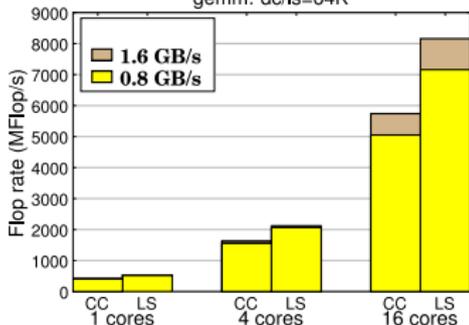
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- SpMV performance scales with memory bandwidth for enough cores

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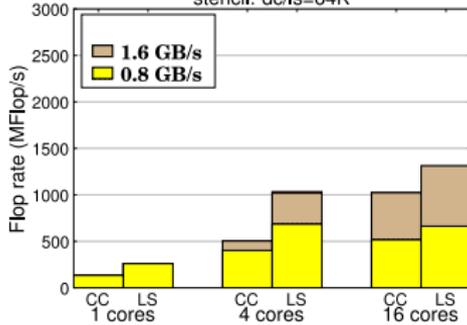
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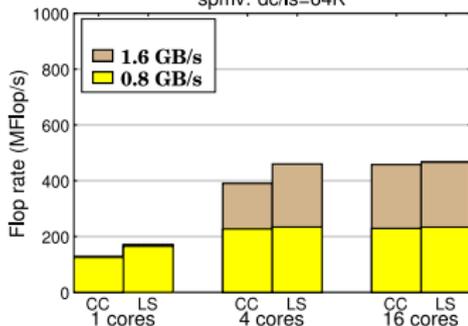
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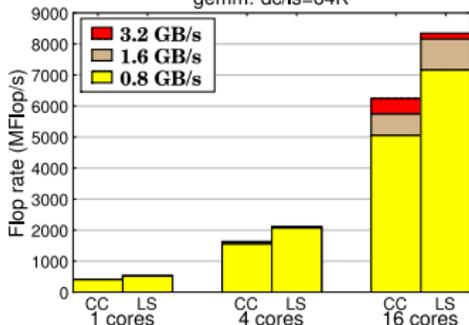
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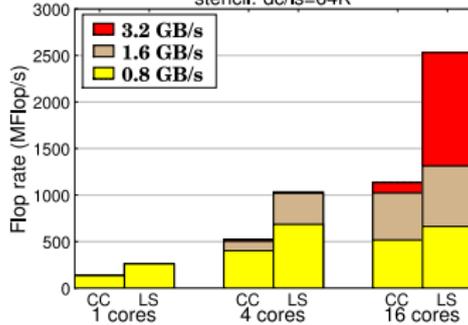
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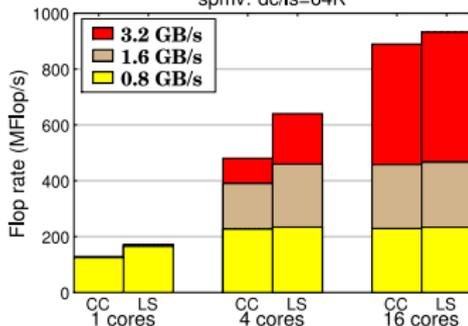
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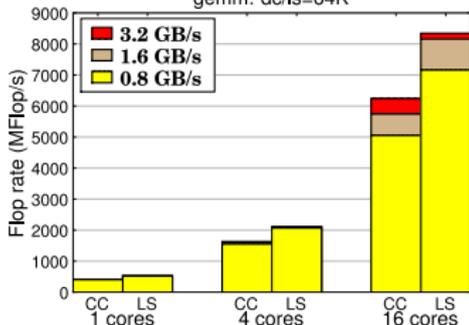
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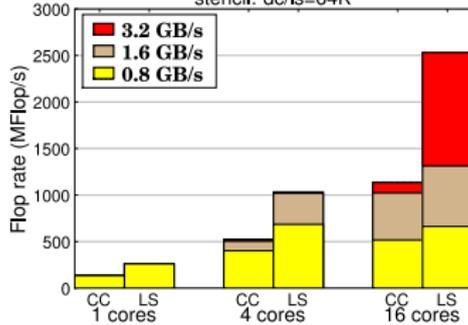
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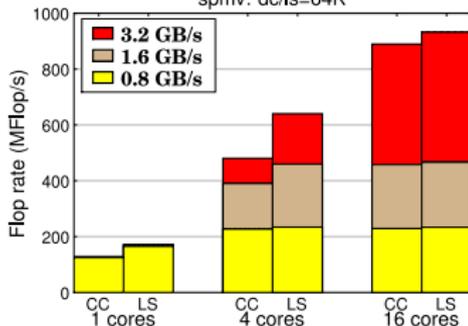
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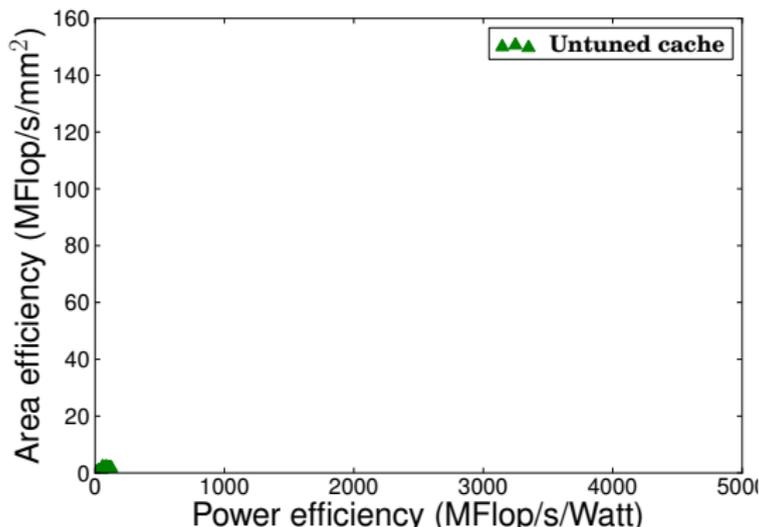
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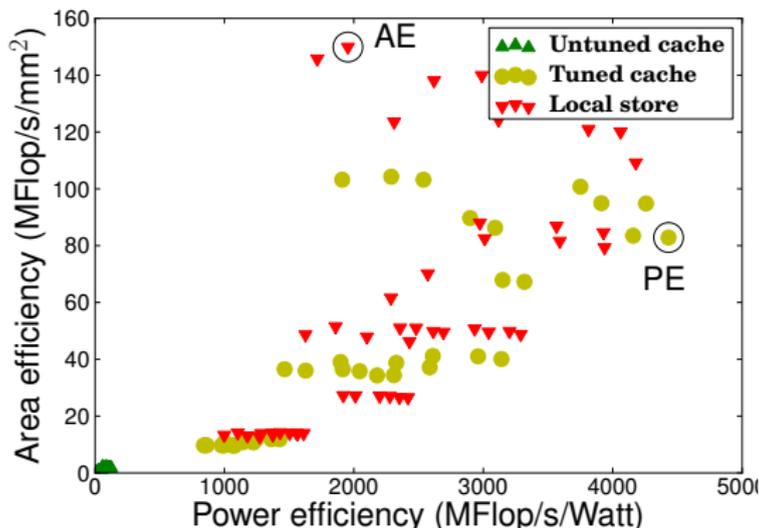
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Efficiency Improvements: GEMM



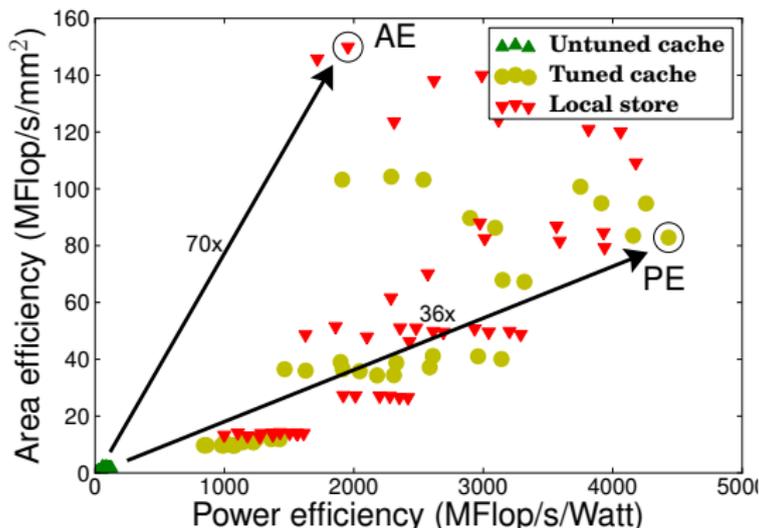
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 - Best SW performance chosen by autotuner used for computing efficiencies
- Efficiency improvements from SW tuning dramatic

Efficiency Improvements: GEMM



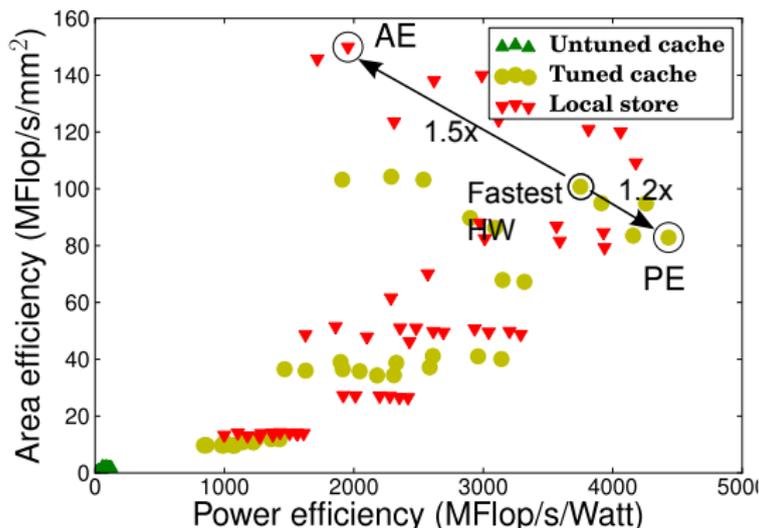
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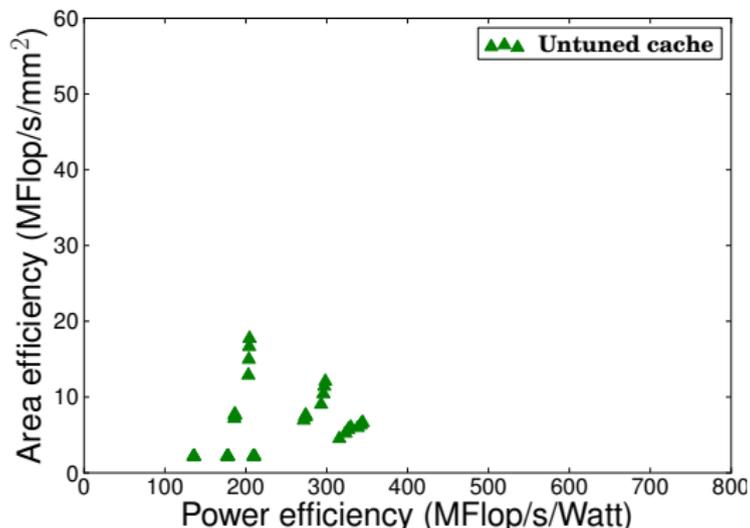
- Each point represent a HW config (AE = most area efficient, PE = most power efficient)
 - Best SW performance chosen by autotuner used for computing efficiencies
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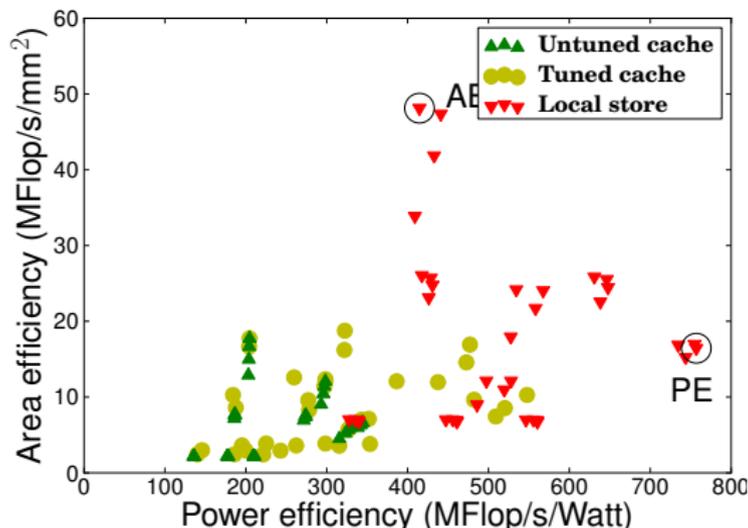
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Efficiency Improvements: Stencil



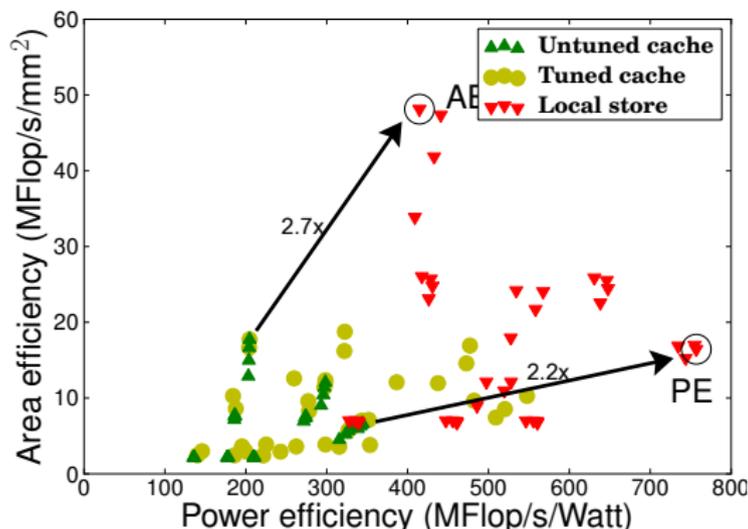
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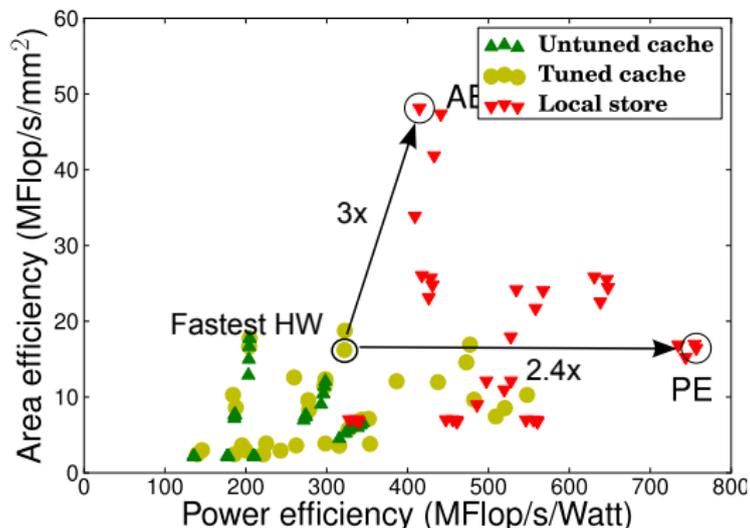
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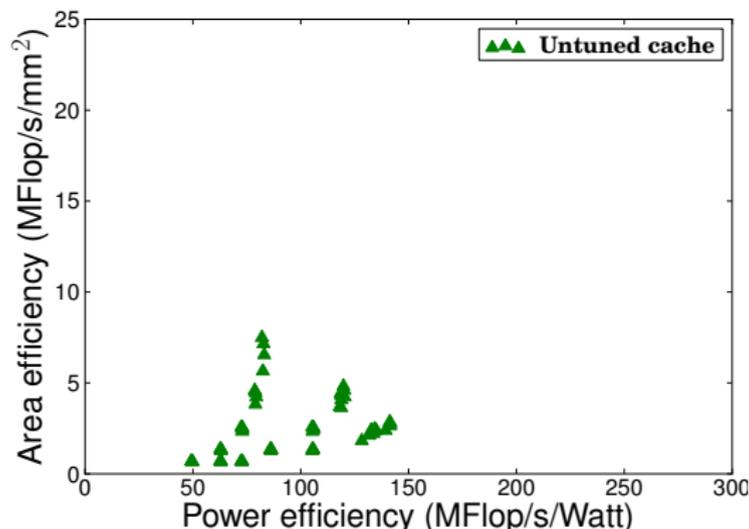
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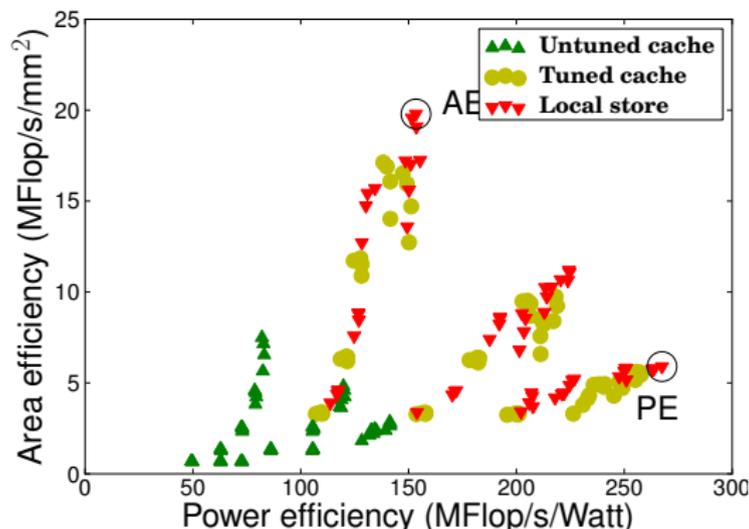
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Efficiency Improvements: SpMV



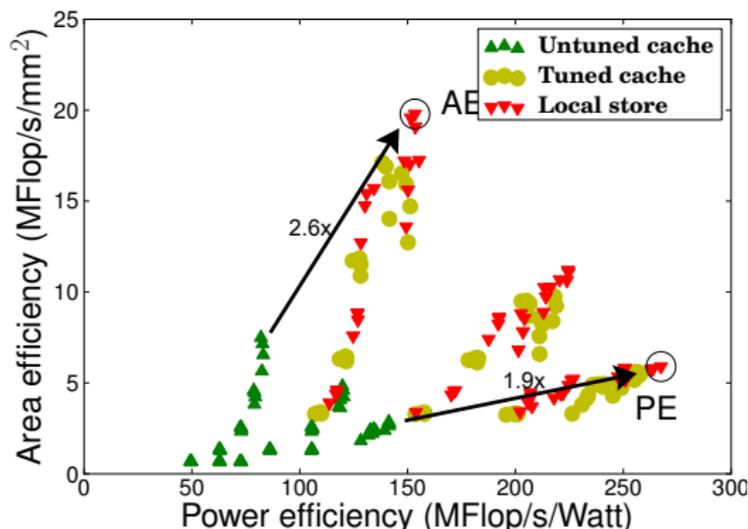
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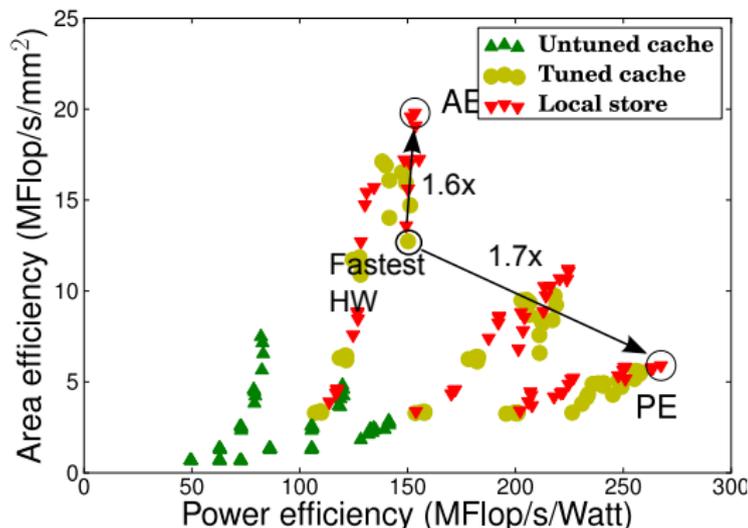
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Co-tuning for multiple kernels

- Results so far find best HW config given kernel
- How about an application composed of multiple kernels?
- Simple case: kernels dont interact, all flops contributed by the given kernels
 - ⇒ sufficient to tune kernels instead of full application
 - Performance/power for application on a HW config = weighted performance/power of kernels on the config
 - Weights = relative contribution of different kernels

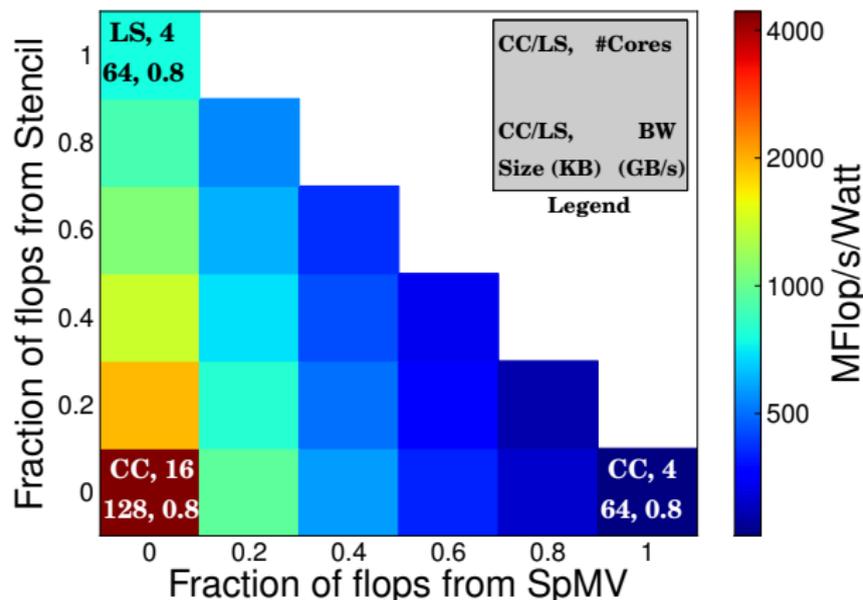
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Tuning Multi-Kernel Application



Each box represents the most power-efficient HW config for the given relative weights of kernels

Summary of results

- Baseline: SW tuning done on the fastest HW config
- GEMM: $1.2\times$ and $1.5\times$ improvements in power and area efficiencies
- Stencil: $2.4\times$ and $3\times$ improvements in power and area efficiencies
- SpMV: $1.7\times$ and $1.6\times$ improvements in power and area efficiencies
- Weighted combination of GEMM, stencil, SpMV: improvements vary from $1.2\times$ to $2.4\times$ depending on relative contribution

- 1 Background
- 2 Experimental Setup
- 3 Results
- 4 Conclusions and Future Work**

- Novel approach to designing power-efficient supercomputers
 - Leverage software auto-tuning to improve efficiency
 - Power efficiency improved $1.2\text{--}2.4\times$,
area efficiency improved $1.5\text{--}3\times$
 - Improvements also in multi-kernel applications
 - Co-tuning can cut down procurement and running costs
- Future work
 - Explore a larger HW design space
⇒ need intelligent exploration
 - Use FPGA-based emulation of hardware for speeding up exploration
 - Efficiently co-tuning for applications with interacting kernels
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Questions?

Kernel 3: Matrices

spyplot	Name	Dimensions	Nonzeros (nnz/row)	Description
	Dense	2K x 2K	4.0M (2K)	Dense matrix in sparse format
	FEM / Spheres	83K x 83K	6.0M (72)	FEM concentric spheres
	FEM / Cantilever	62K x 62K	4.0M (65)	FEM cantilever
	Wind Tunnel	218K x 218K	11.6M (53)	Pressurized wind tunnel
	QCD	49K x 49K	1.90M (39)	Quark propagators (QCD/LGT)
	FEM/Ship	141K x 141K	3.98M (28)	FEM Ship section/detail
	Epidemiology	526K x 526K	2.1M (4)	2D Markov model of epidemic
	Circuit	171K x 171K	959K (6)	Motorola circuit simulation

- SpMV performance dependent on matrix nonzero pattern
- Matrices chosen to represent different applications
- Dense matrix in sparse format used for tuning
- For each HW config, SpMV performance = performance of median matrix